STOCHASTIC THERMODYNAMICS OF DISTRIBUTED SYSTEMS

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$$\frac{dp_i(t)}{dt} = \sum_j K_{ij}(t)p_j(t)$$

- Example: Dynamics of a Turing Machine
- Example: (Noisy) dynamics of a digital gate in a circuit
- Example: (Noisy) dynamics of an entire digital circuit
- Example: Spike train going down an axon
- Example: Neuronal assemblies communicating

$$\frac{dp_i(t)}{dt} = \sum_j K_{ij}(t)p_j(t)$$

Just for fun, let's see how Shannon entropy of p evolves under this equation

$$\begin{aligned} \frac{dp_i(t)}{dt} &= \sum_j K_{ij}(t)p_j(t) \\ \frac{dS(p(t))}{dt} &= \dot{Q}(t) + \dot{\Sigma}(t) \\ \bullet \ \dot{Q}(t) &= \sum_{ij} K_{ij}(t)p_j(t) \ln \frac{K_{ji}(t)}{K_{ij}(t)} & \text{Entropy flow rate} \\ \bullet \ \dot{\Sigma}(t) &= \sum_{ij} K_{ij}(t)p_j(t) \ln \frac{K_{ij}(t)p_j(t)}{K_{ji}(t)p_i(t)} & \text{Entropy production rate} \end{aligned}$$

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• Entropy production (EP) rate is non-negative

Consider a master equation that sends $p_0(x)$ to $p_1(x) = \sum_{x_0} P(x_1 | x_0) p_0(x)$

$$\frac{dp_i(t)}{dt} = \sum_j K_{ij}(t)p_j(t)$$
$$\frac{dS(p(t))}{dt} = \dot{Q}(t) + \dot{\Sigma}(t)$$

Integrate over time: $-\Delta Q = \Delta \Sigma - \Delta S$

- $\Delta S = S(p_1) S(p_0)$ is gain in Shannon entropy of p
- $-\Delta Q$ is (Shannon) entropy flow from system between t = 0 and t = 1
- ΔΣ is total entropy production in system between t = 0 and t = 1
 <u>cannot be negative</u>

(I.e., the second law of thermodynamics)

GENERALIZED LANDAUER BOUND

- System connected to multiple reservoirs, e.g., heat baths at different temperatures. (So " $k_{\rm B}T$ " not defined.)
- Arbitrary number of states
- Arbitrary initial distribution p₀
- Arbitrary dynamics P(x₁ | x₀)

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$$-\Delta Q = \Delta \Sigma + S(p_0) - S(p_1)$$

Entropy Production ($\Delta \Sigma$) is non-negative. So:

"Generalized Landauer's bound":

Entropy flow (i.e., $-\Delta Q$) $\geq S(p_0) - S(p_1)$

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$$-\Delta Q$$
) $\geq S(p_0) - S(p_1)$

• Assume local detailed balance

Then: -\(\Delta\) *Q is (temperature-normalized) heat flow into environment*

EXAMPLE – LANDAUER'S CONCLUSION

- System evolves while connected to <u>single</u> heat bath at temperature T Then heat flow into environment = $-k_{\rm B}T \Delta Q$
- Two possible states
- p₀ uniform
- Process implements bit erasure (so p_1 a delta function)
- Assume local detailed balance

So generalized Landauer's bound says

Total heat flow into environment $\geq k_{\rm B} T \ln[2]$

Landauer's conclusion

(Parrondo et al., *Nature Physics 2015*, Sagawa, *J. Stat. Mech. 2014*, Hasegawa et al., *Phys. Letters A 2010*, Wolpert, *Entropy 2015*, etc.)

IMPLICATATION OF GENERALIZED LANDAUER BOUND

$-\Delta Q = \Delta \Sigma + S(p_0) - S(p_1)$

p₀ is initial distribution, i.e., distribution over inputs. *Fixed by environment / previous computations*.

p₁ is ending distribution, i.e., distribution over outputs. - *Fixed by the (possibly noisy) computation,* $P(x_1 | x_0)$

> Increasing noise in computation (increases entropy of ending distribution and so) reduces minimal thermodynamic cost

WHAT IS REALLY IMPORTANT THERMODYNAMICALLY?

$-\Delta Q = \Delta \Sigma + S(p_0) - S(p_1)$

- System evolves while connected to <u>single</u> heat bath at temperature T Then heat flow into environment = $-k_{\rm B}T \Delta Q$
- At scale of real computers and brains, $k_B T[S(p_0) S(p_1)]$ is small
- At scale of real computers and brains, $\Delta \Sigma$ is dominant cost

What determines $\Delta \Sigma$?

1) Given a fixed computer, <u>varying distribution over inputs</u> changes expected thermodynamic costs – how exactly?

In particular, how does EP generated by a fixed process $P(x_1 | x_0)$ depend on the initial distribution, $P(x_0)$?

Dependence of EP on initial distribution

- Arbitrary dynamics P(x₁ | x₀)
- Assume system is thermo. reversible for initial distribution q₀
- I.e., $\Delta \Sigma(q_0) = 0$

• Run that system with initial distribution $p_0 \neq q_0$ instead:

$$\Delta \Sigma(p_0) = D(p_0 || q_0) - D(p_1 || q_1)$$

$$\geq 0$$

where D(. || .) is relative entropy (KL divergence)

Wolpert, D., Kolchinsky, A., *New J. Phys.* (2020) Riechers, P., Gu, M., *Phys. Rev. E* (2021) Kolchinsky, A., Wolpert D., *arxiv:2103.05734*

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Any nontrivial process that is thermodynamically reversible for one initial distribution will not be for any other initial distribution

- **Two** distinct bit-erasing gates, each with thermo. rev. initial distribution q_0
- Run gates in parallel, on bits x^A and x^B , with initial distribution $p_0(x^A, x^B)$
- Assume $p_0(x^A) = q_0(x^A)$ and $p_0(x^B) = q_0(x^B)$.
- So each gate, by itself, generates zero EP. But:

If $p_0(x^A, x^B)$ statistically couples the bits, then full system is **not** thermo. reversible, and generates nonzero EP

• Formally: Since gates are distinct, the thermo. rev. *joint* distribution is $q_0(x^A, x^B) = q_0(x^A)q_0(x^B)$.

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 Intuition: Running two thermo. reversible gates in parallel loses information in their initial coupling, and so is not thermo. reversible.

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• Broader lesson: Modularity increases EP

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• **Broader lesson**: Whatever its benefits might be,

modularity is thermodynamically costly (!)

Example - Thermodynamics of circuits

- Currently, all mass-produced computers are implemented with circuits.
- The simplest circuit is one without loops or branches (a "straight-line program")
- If set of allowed gates are a universal basis (e.g., NAND gates), then can build a circuit with them to implement any desired Boolean function.



$-\Delta Q = \Delta \Sigma + S(p_0) - S(p_1)$

- For fixed $P(x_1 | x_0)$, changing p_0 changes $S(p_0) S(p_1)$
- N.b., the same P(x₁ | x₀) e.g., same AND gate has different p₀, depending on where it is in a circuit.
- So even for a thermo. reversible gate (∆∑(p₀) = 0), changing the gate's location in a circuit (changes S(p₀) S(p₁) and so) changes -∆Q(p₀)



- Changing a gate's location in a circuit changes S(p₀) − S(p₁), and so changes the heat it produces, -∆Q(p₀)
- Sum those heats over all gates to get minimal heat flow of that circuit

Different circuits implementing <u>same</u> Boolean function on <u>same</u> input distribution have <u>different</u> minimal heat

- Formally, those differences in minimal heat of the circuits are differences in EPs of the circuits, arising due to modularity of gates
 - A new circuit design optimization problem



NOTATION:

 $I(P(X_1, X_2, \dots)) = [\sum_i S(P(X_i))] - S(P(X_1, X_2, \dots))$

- "Multi-information" (also called "total correlation")
- A generalization of mutual information
- Quantifies how much information is shared among the X_i

WHAT CIRCUIT TO COMPUTE A GIVEN FUNCTION f?

(Partial) answer: Assume each gate re-initializes the upstream gates that provided its input.

Then change in total Landauer cost if use circuit C' rather than C to compute f:

$$\sum_{g \in C'} I(p^{pa(g)}) - \sum_{g \in C} I(p^{pa(g)})$$

where g indexes gates.

I.e., choose circuit that implements f with *smallest sum of multi-informations* of input distributions into its gates.

Wolpert, D., Kolchinsky, A., New J. Physics (2020)

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A global circuit design optimization problem.

Wolpert, D., Kolchinsky, A., New J. Physics (2020)

At the macroscopic scale, expected entropy cannot decrease; Can <u>always</u> tell if a movie of a macroscopic process runs backward

At the microscopic scale, expected entropy cannot change; Can never tell if a movie of a microscopic process runs backward

What happens at mesoscopic scale?

Consider a (perhaps time-varying) master equation

$$\frac{dp_i(t)}{dt} = \sum_j K_{ij}(t)p_j(t)$$
$$\frac{dS(p(t))}{dt} = \dot{Q} + \dot{\Sigma}$$
$$\cdot \quad \dot{Q} = -\sum_{ij} K_{ij}p_j(t)\ln\left[\frac{K_{ji}}{K_{ij}}\right]$$
$$\cdot \quad \dot{\Sigma} = \sum_{ij} K_{ij}p_j(t)\ln\left[\frac{K_{ij}p_j(t)}{K_{ji}p_i(t)}\right]$$

These are expectations over trajectories.

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These are <u>expectations over trajectories</u>. Can also define trajectory-level thermodynamic quantities:

- Stochastic entropy if system in state i at time t: $s_i(t) = -\ln p_i(t)$
- Expectation of stochastic entropy is Shannon entropy, S(p(t))

Can define trajectory-level thermodynamic quantities.

• Stochastic entropy if system in state i at time t: $s_i(t) = -\ln p_i(t)$

Integral fluctuation theorem (FT) constrains the average over trajectories of total (timeintegrated) EP along a trajectory:

$$\langle e^{-kT\sigma} \rangle = 1$$

(Seifert, Reports on Progress in Physics, 2012)

Can define trajectory-level thermodynamic quantities.

• Stochastic entropy if system in state i at time t: $s_i(t) = -\ln p_i(t)$

Integral fluctuation theorem (FT) constrains the average over trajectories of total (timeintegrated) EP along a trajectory:

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• Apply Jensen's inequality: expected EP over trajectories is non-negative – second law, as before.

• But nonzero probability that in any single trajectory, EP < 0

Can define trajectory-level thermodynamic quantities.

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Integral fluctuation theorem (FT) constrains the average over trajectories of total (timeintegrated) EP along a trajectory:

$$\langle e^{-kT\sigma} \rangle = 1$$

• But nonzero probability that in any single trajectory, EP < 0

- Quantifies probability that at any scale, movie runs backward

THERMODYNAMIC UNCERTAINTY RELATIONS (TURs)

- **x** is a *trajectory* of system states during a given time interval
- A current J(x) is any (!) function of the state transitions in x that is odd under time-reversal

Examples: Net charge flow from anode to diode; Net number of times a particular neuron fires; Net value of predictive coding error signals.

 In many conditions (e.g., a steady state) a *Thermodynamic Uncertainty Relation* bounds current statistical precision by ∆∑:



• **Example**: If variance in predictive coding error signals is small, then small expected errors is <u>necessary</u> for small thermodynamic cost

Accurate predictions in predictive coding is necessary to have low energetic cost

THERMODYNAMICS OF CO-EVOLVING COMPUTERS

- Many examples of multiple asynchronous co-evolving computers organelles in a cell neurons in a brain organs in a biological organism humans in a social organization
- Network topology of interactions has major thermodynamic consequences





Much of conventional stochastic thermodynamics

- including (almost) all FTs and TURs -

is formulated for single systems, not multiple interacting systems



- B is level of ligand concentration in medium
- A is cell wall detectors of ligand concentration
- C is cell wall detectors of ligand concentration



- Red arrows indicate dependencies of rate matrices of the three systems
- N.b., $\{B\}$ evolves independently, but is observed by $\{A\}$ and $\{C\}$
- $\{A\}$ and $\{C\}$ not *physically* coupled, but become *statistically* coupled with time





A *unit r* is a set of systems that evolve autonomously

• $\{AB\}, \{B\}, and \{BC\}$ are units





A *unit r* is a set of systems that evolve autonomously

• Each unit has its own master equation, its own EP, own FTs, own TURs, etc.





A *unit r* is a set of systems that evolve autonomously

How are fluctuations in EPs of the units coupled?



• *Conditional* integral fluctuation theorem: For any unit r,

$$\langle e^{\sigma^r - \sigma} | \sigma^r \rangle = 1$$



Conditional integral fluctuation theorem: For any unit r, ٠

$$\langle e^{\sigma^r - \sigma} | \sigma^r \rangle = 1$$

- System-wide EP for trajectory **x**: $\sigma(\mathbf{x}) = \widehat{\sum}_{r'} \sigma^{r'}(\mathbf{x}) \Delta I^*(\mathbf{x})$ $\widehat{\Sigma}_{r'} \sigma^{r'}(\mathbf{x})$ is "inclusion-exclusion sum", of unit EPs over trajectory **x** •

 - $\Delta I^*(\mathbf{x})$ is (change in) "inclusion-exclusion sum" of Shannon entropies



Conditional integral fluctuation theorem: For any unit r, ٠

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Combining: For any unit r,

$$\widehat{\sum}_{r'} \left\langle \sigma^{r'} \right\rangle - \left\langle \Delta I^* \right\rangle \geq \left\langle \sigma^r \right\rangle$$

Speed limit theorem for interacting systems



$$\widehat{\sum}_{r'} \left\langle \sigma^{r'} \right\rangle - \left\langle \Delta I^* \right\rangle \geq \left\langle \sigma^r \right\rangle$$

• Using this result repeatedly for different choices of unit *r* gives:

$$\min\left[\left\langle \sigma^{BC} \right\rangle, \left\langle \sigma^{AB} \right\rangle\right] - \left\langle \sigma^{B} \right\rangle \geq \Delta I(A; C \mid B)$$

where I(A; C | B)(t) is mutual information between the two types of receptor, conditioned on ligand concentration level

• So if want to change conditional mutual information a lot during fixed time interval, must pay for it with large EP of both the units BC and AC

Strengthened second law for interacting systems



• If ligand concentration is constant in time, *total* EP of full system is bounded by

$\langle \sigma \rangle \ge -\Delta I(A; C \mid B) \ge 0$

• A larger lower bound on total EP of full system than the second law,

reflecting informational coupling among ligand concentration and two receptor types

New kind of TUR



- Suppose ligand concentration in stationary state, so standard TUR applies to that system, *but overall system does not obey conditions for any conventional TUR*.
- <u>So conventional TUR does not apply to overall system</u>
- Even so: $\langle \sigma \rangle \ge \frac{2k \langle J_B \rangle^2}{\operatorname{Var}(J_B)} + \max \left[\Delta I(A; C \mid B), 0 \right]$
- So if ligand concentration varies in a noisy cyclic process, and is in a stationary state, then the less noise in the cycling, the more EP is produced by full system

Strengthened second law for interacting systems



• Suppose all rate matrices constant in time (no mechanical work), and first receptor is in a stationary state:

$$\langle \sigma \rangle \geq \left\langle \sigma^{AB} \right\rangle + \left\langle \sigma^{BC} \right\rangle$$

• A larger lower bound on total EP of full system than the second law, reflecting structure of interactions among the three systems

New kind of TUR



- Suppose that in addition, ligand concentration starts in equilibrium. Then joint system AB would be in stationary state. However, joint system BC is relaxing to equilibrium.
- Systems AB and BC obey *different* TURs, and no conventional TUR applies to full system

• Even so:
$$\langle \sigma \rangle \ge \frac{2k \langle J_{AB} \rangle^2}{\operatorname{Var}(J_{AB})} + \frac{2[\tau \ j_{BC}(\tau)]^2}{\operatorname{Var}(J_{BC}(\tau))}$$

CONCLUSIONS

• Exact equations for entire entropy flow of a system:

 $EF(p_0) = Landauer cost (p_0) + EP(p_0)$

- Thermodynamic Kolmogorov complexity is bounded (unlike conventional Kolmogorov complexity)
- Average work to run a TM is infinite
- Different circuits, all implementing the same function, all using thermodynamically reversible gates, have different thermodynamic costs.
- Very difficult problems of finding least-cost circuit for a given function.
- For real digital computers, brains, etc., dominant cost is EP(p₀), not Landauer cost
- TURs, speed limit theorems, mismatch cost, all provide lower bounds on EP(p₀) arising from how a computer is used and how it performs.

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