STOCHASTIC THERMODYNAMICS OF DISTRIBUTED SYSTEMS

David H. Wolpert (Santa Fe Institute)

SANTA FE INSTITUTE

The Abdus Salam International Centre for Theoretical Physics

$$
\frac{dp_i(t)}{dt} = \sum_j K_{ij}(t)p_j(t)
$$

- Example: Dynamics of a Turing Machine
- Example: (Noisy) dynamics of a digital gate in a circuit
- Example: (Noisy) dynamics of an entire digital circuit
- Example: Spike train going down an axon
- Example: Neuronal assemblies communicating

$$
\frac{dp_i(t)}{dt} = \sum_j K_{ij}(t)p_j(t)
$$

Just for fun, let's see how Shannon entropy of p evolves under this equation

$$
\frac{dp_i(t)}{dt} = \sum_j K_{ij}(t)p_j(t)
$$
\n
$$
\frac{dS(p(t))}{dt} = \dot{Q}(t) + \dot{\Sigma}(t)
$$
\n•
$$
\dot{Q}(t) = \sum_{ij} K_{ij}(t)p_j(t) \ln \frac{K_{ji}(t)}{K_{ij}(t)}
$$
\nEntropy flow rate

\n•
$$
\dot{\Sigma}(t) = \sum_{ij} K_{ij}(t)p_j(t) \ln \frac{K_{ij}(t)p_j(t)}{K_{ji}(t)p_i(t)}
$$
\nEntropy production rate

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\nEntropy production rate

• *Entropy production (EP) rate is non-negative*

Consider a master equation that sends $p_0(x)$ to $p_1(x) = \sum_{x_0} P(x_1 | x_0) p_0(x)$

$$
\frac{dp_i(t)}{dt} = \sum_j K_{ij}(t)p_j(t)
$$

$$
\frac{dS(p(t))}{dt} = \dot{Q}(t) + \dot{\Sigma}(t)
$$

Integrate over time: $-\Delta Q = \Delta \Sigma - \Delta S$

- $\Delta S = S(p_1) S(p_0)$ is gain in Shannon entropy of p
- $-\Delta Q$ is (Shannon) entropy flow from system between $t = 0$ and $t = 1$
- $\Delta \Sigma$ is total entropy production in system between t = 0 and t = 1 - *cannot be negative*

(I.e., the second law of thermodynamics)

GENERALIZED LANDAUER BOUND

- System connected to multiple reservoirs, e.g., heat baths at different temperatures. (So " $k_B T$ " not defined.)
- Arbitrary number of states
- Arbitrary initial distribution p_0
- Arbitrary dynamics $P(x_1 | x_0)$

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$$
-\Delta Q = \Delta \Sigma + S(p_0) - S(p_1)
$$

Entropy Production $(\Delta \Sigma)$ is non-negative. So:

"<u>Generalized Landauer's bound":</u>

Entropy flow (i.e., $-\Delta Q$) ≥ *S*(p_0) – *S*(p_1)

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"<u>Generalized Landauer's bound":</u>

Entropy flow (i.e.,
$$
-\Delta Q
$$
) \geq S(p_0) - S(p_1)

• Assume local detailed balance

Then: - ΔQ is (temperature-normalized) heat flow into environment

EXAMPLE – LANDAUER'S CONCLUSION

- System evolves while connected to *single* heat bath at temperature *T* Then heat flow into environment = $-k_{\rm B}T \Delta Q$
- Two possible states
- p_0 uniform
- Process implements bit erasure (so p_1 a delta function)
- Assume local detailed balance

So generalized Landauer's bound says

Total heat flow into environment $\geq k_{\rm B}T \ln[2]$

Landauer's conclusion

(Parrondo et al*., Nature Physics 2015,* Sagawa*, J. Stat. Mech. 2014,* Hasegawa et al., *Phys. Letters A 2010,* Wolpert, *Entropy 2015, etc.*)

IMPLICATATION OF GENERALIZED LANDAUER BOUND

$$
-\Delta Q = \Delta \Sigma + S(p_0) - S(p_1)
$$

 p_0 is initial distribution, i.e., distribution over inputs. - *Fixed by environment / previous computations.*

 p_1 is ending distribution, i.e., distribution over outputs. - *Fixed by the (possibly noisy) computation,* $P(x_1 | x_0)$

> *Increasing noise in computation (increases entropy of ending distribution and so) reduces minimal thermodynamic cost*

WHAT IS REALLY IMPORTANT THERMODYNAMICALLY?

$-\Delta Q = \Delta \Sigma + S(p_0) - S(p_1)$

- System evolves while connected to *single* heat bath at temperature *T* Then heat flow into environment = $-k_{\rm B}T \Delta Q$
- At scale of real computers and brains, $k_{\rm B}T[S(p_0) S(p_1)]$ is small
- At scale of real computers and brains, ∆! **is dominant cost**

What determines $\Delta \Sigma$?

1) Given a fixed computer, varying distribution over inputs changes expected thermodynamic costs – how exactly?

> In particular, *how does EP generated by a fixed process* $P(x_1 | x_0)$ *depend on the initial distribution,* $P(x_0)$?

Dependence of EP on initial distribution

- Arbitrary dynamics $P(x_1 | x_0)$
- *Assume system is thermo. reversible for initial distribution q0*
- l.e., $\Delta\Sigma(q_o) = 0$

• Run that system with initial distribution $p_0 \neq q_0$ instead:

$$
\Delta \Sigma(p_0) = D(p_0 || q_0) - D(p_1 || q_1)
$$

\n
$$
\geq 0
$$

where D(. || .) is relative entropy (KL divergence)

Wolpert, D., Kolchinsky, A., *New J. Phys.* (2020) Riechers, P.. Gu, M., *Phys. Rev. E* (2021) Kolchinsky, A., Wolpert D., *arxiv:2103.05734*

Dependence of EP on initial distribution

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Any nontrivial process that is thermodynamically reversible for one initial distribution will not be for any other initial distribution

- **Two** distinct bit-erasing gates, each with thermo. rev. initial distribution q_0
- Run gates in parallel, on bits x^A and x^B , with initial distribution $p_0(x^A, x^B)$
- Assume $p_0(x^A) = q_0(x^A)$ and $p_0(x^B) = q_0(x^B)$.
- So each gate, by itself, generates zero EP. But:

If $p_0(x^A, x^B)$ *statistically couples the bits, then full system is* **not** *thermo. reversible, and generates nonzero EP*

• **Formally**: Since gates are distinct, the thermo. rev. *joint* distribution is $q_0(x^A, x^B) = q_0(x^A)q_0(x^B).$

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• **Intuition**: **Running two thermo. reversible gates in parallel loses information in their initial coupling, and so is not thermo. reversible**.

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• **Broader lesson**: *Modularity increases EP*

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Broader lesson: Whatever its benefits might be,

modularity is thermodynamically costly (!)

Example - Thermodynamics of circuits

- Currently, all mass-produced computers are implemented with circuits.
- The simplest circuit is one without loops or branches (a "straight-line program")
- If set of allowed gates are a universal basis (e.g., NAND gates), then can build a circuit with them to implement any desired Boolean function.

$-\Delta Q = \Delta \Sigma + S(p_0) - S(p_1)$

- For fixed $P(x_1 | x_0)$, changing p_0 changes $S(p_0) S(p_1)$
- N.b., the same $P(x_1 | x_0) e.g.$, same AND gate has different p_0 , depending on where it is in a circuit.
- So even for a thermo. reversible gate $(\Delta \Sigma(p_0) = 0)$, **changing the gate's** *location in a circuit* (changes $S(p_0) - S(p_1)$ and so) *changes -* $\Delta Q(p_0)$

- Changing a gate's location in a circuit changes $S(p_0) S(p_1)$, and so changes the heat it produces, $-\Delta Q(\rho_0)$
- Sum those heats over all gates to get minimal heat flow of that circuit

Different circuits implementing *same* Boolean function on *same* input distribution have *different* minimal heat

- Formally, those differences in minimal heat of the circuits are differences in EPs of the circuits, arising due to modularity of gates
	- \triangleright A new circuit design optimization problem

NOTATION:

 $I(P(X_1, X_2, ...)$ = $[\sum_i S(P(X_i))] - S(P(X_1, X_2, ...)$

- "Multi-information" (also called "total correlation")
- A generalization of mutual information
- Quantifies how much information is shared among the *Xi*

WHAT CIRCUIT TO COMPUTE A GIVEN FUNCTION f?

(Partial) answer: Assume each gate re-initializes the upstream gates that provided its input.

Then change in total Landauer cost if use circuit C′ rather than C to compute f:

$$
\sum_{g \in C'} I(p^{pa(g)}) - \sum_{g \in C} I(p^{pa(g)})
$$

where g indexes gates.

I.e., choose circuit that implements f with *smallest sum of multi-informations* of input distributions into its gates.

Wolpert, D., Kolchinsky, A., New J. Physics (2020)

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A *global* circuit design optimization problem**.**

Wolpert, D., Kolchinsky, A., New J. Physics (2020)

At the macroscopic scale, expected entropy cannot decrease; *Can* always *tell if a movie of a macroscopic process runs backward*

At the microscopic scale, expected entropy cannot change; *Can* never *tell if a movie of a microscopic process runs backward*

What happens at mesoscopic scale?

Consider a (perhaps time-varying) master equation

$$
\frac{dp_i(t)}{dt} = \sum_j K_{ij}(t)p_j(t)
$$
\n
$$
\frac{dS(p(t))}{dt} = \dot{Q} + \dot{\Sigma}
$$
\n
$$
\dot{Q} = -\sum_{ij} K_{ij}p_j(t) \ln\left[\frac{K_{ji}}{K_{ij}}\right]
$$
\n
$$
\dot{\Sigma} = \sum_{ij} K_{ij}p_j(t) \ln\left[\frac{K_{ij}p_j(t)}{K_{ji}p_i(t)}\right]
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These are expectations over trajectories.

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$$

These are expectations over trajectories. Can also define trajectory-level thermodynamic quantities:

- Stochastic entropy if system in state i at time t: $s_i(t) = -\ln p_i(t)$
- Expectation of stochastic entropy is Shannon entropy, $S(p(t))$

Can define trajectory-level thermodynamic quantities.

• Stochastic entropy if system in state i at time t: $s_i(t) = -\ln p_i(t)$

Integral fluctuation theorem (FT) constrains the average over trajectories of total (timeintegrated) EP along a trajectory:

$$
\langle e^{-kT\sigma} \rangle = 1
$$

(Seifert, Reports on Progress in Physics, 2012)

Can define trajectory-level thermodynamic quantities.

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Integral fluctuation theorem (FT) constrains the average over trajectories of total (timeintegrated) EP along a trajectory:

$$
\langle e^{-kT\sigma}\rangle = 1
$$

• *Apply Jensen's inequality: expected EP over trajectories is non-negative – second law, as before.*

• *But nonzero probability that in any single trajectory, EP < 0*

Can define trajectory-level thermodynamic quantities.

• Stochastic entropy if system in state i at time t: $s_i(t) = -\ln p_i(t)$

Integral fluctuation theorem (FT) constrains the average over trajectories of total (timeintegrated) EP along a trajectory:

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$$

• *But nonzero probability that in any single trajectory, EP < 0*

- Quantifies probability that at any scale, movie runs backward

THERMODYNAMIC UNCERTAINTY RELATIONS (TURs)

- *x* is a *trajectory* of system states during a given time interval
- A *current J*(*x*) is any (!) function of the state transitions in *x* that is odd under time-reversal

Examples: Net charge flow from anode to diode; Net number of times a particular neuron fires; Net value of predictive coding error signals.

• In many conditions (e.g., a steady state) a *Thermodynamic Uncertainty Relation* bounds current statistical precision by $\Delta \Sigma$:

Example: If variance in predictive coding error signals is small, then small expected errors is *necessary* for small thermodynamic cost

> *Accurate predictions in predictive coding is necessary to have low energetic cost*

THERMODYNAMICS OF CO-EVOLVING COMPUTERS

- Many examples of multiple asynchronous co-evolving computers organelles in a cell neurons in a brain organs in a biological organism humans in a social organization
- Network topology of interactions has major thermodynamic consequences

Much of conventional stochastic thermodynamics

– including (almost) all FTs and TURs –

is formulated for single systems, *not* multiple interacting systems

- B is level of ligand concentration in medium
- A is cell wall detectors of ligand concentration
- C is cell wall detectors of ligand concentration

- Red arrows indicate dependencies of rate matrices of the three systems
- N.b., ${B}$ evolves independently, but is observed by ${A}$ and ${C}$
- {A} and {C} not *physically* coupled, but become *statistically* coupled with time

A *unit r* is a set of systems that evolve autonomously

• ${AB}, {B}, and {BC}$ are units

A *unit r* is a set of systems that evolve autonomously

• Each unit has its own master equation, its own EP, own FTs, own TURs, etc.

A *unit r* is a set of systems that evolve autonomously

How are fluctuations in EPs of the units coupled?

• *Conditional* integral fluctuation theorem: For any unit r,

$$
\langle e^{\sigma^r-\sigma}|\sigma^r\rangle=1
$$

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$$
\langle e^{\sigma^r-\sigma}|\sigma^r\rangle=1
$$

- System-wide EP for trajectory **x**:
	- $-\hat{\Sigma}_{r'}$ $\sigma^{r'}(x)$ is "inclusion-exclusion sum", of unit EPs over trajectory **x**

 $-\Delta I^*(\mathbf{x})$ is (change in) "inclusion-exclusion sum" of Shannon entropies

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Combining: For *any* unit r,

$$
\widehat{\sum}_{\tau'}\left<\sigma^{\tau'}\right>-\left<\Delta I^*\right>\geq\left<\sigma^{\tau}\right>
$$

Speed limit theorem for interacting systems

$$
\widehat{\sum}_{r'}\left\langle \sigma^{r'}\right\rangle -\left\langle \Delta I^{*}\right\rangle \geq\left\langle \sigma^{r}\right\rangle
$$

• Using this result repeatedly for different choices of unit *r* gives:

$$
\min\left[\left\langle \sigma^{BC}\right\rangle ,\left\langle \sigma^{AB}\right\rangle \right]-\left\langle \sigma^{B}\right\rangle \geq\Delta I(A;C\,|\,B)
$$

where $I(A; C | B)(t)$ is mutual information between the two types of receptor, conditioned on ligand concentration level

• So if want to change conditional mutual information a lot during fixed time interval, must pay for it with large EP of both the units BC and AC

Strengthened second law for interacting systems

• If ligand concentration is constant in time, *total* EP of full system is bounded by

$\langle \sigma \rangle \geq -\Delta I(A;C \mid B) \geq 0$

• A larger lower bound on total EP of full system than the second law,

reflecting informational coupling among ligand concentration and two receptor types

New *kind* of TUR

- Suppose ligand concentration in stationary state, so standard TUR applies to that system, *but overall system does not obey conditions for any conventional TUR*.
- So conventional TUR does not apply to overall system
- Even so: $\langle \sigma \rangle \geq \frac{2k \langle J_B \rangle^2}{\text{Var}(J_B)} + \max \left[\Delta I(A;C | B), 0 \right]$
- So if ligand concentration varies in a noisy cyclic process, and is in a stationary state, then the less noise in the cycling, the more EP is produced by full system

Strengthened second law for interacting systems

• Suppose all rate matrices constant in time (no mechanical work), and first receptor is in a stationary state:

$$
\langle \sigma \rangle \geq \left\langle \sigma^{AB} \right\rangle + \left\langle \sigma^{BC} \right\rangle
$$

• A larger lower bound on total EP of full system than the second law, reflecting structure of interactions among the three systems

New *kind* of TUR

- Suppose that in addition, ligand concentration starts in equilibrium. Then joint system AB would be in stationary state. However, joint system BC is relaxing to equilibrium.
- Systems AB and BC obey *different* TURs, and no conventional TUR applies to full system

• Even so:
$$
\langle \sigma \rangle \ge \frac{2k \langle J_{AB} \rangle^2}{\text{Var}(J_{AB})} + \frac{2[\tau j_{BC}(\tau)]^2}{\text{Var}(J_{BC}(\tau))}
$$

CONCLUSIONS

Exact equations for entire entropy flow of a system:

```
EF(p_0) = Landauer cost (p_0) + EP(p_0)
```
- Thermodynamic Kolmogorov complexity is bounded (unlike conventional Kolmogorov complexity)
- Average work to run a TM is infinite
- Different circuits, all implementing the same function, all using thermodynamically reversible gates, have different thermodynamic costs.
- Very difficult problems of finding least-cost circuit for a given function.
- For real digital computers, brains, etc., dominant cost is $\text{EP}(p_0)$, not Landauer cost
- TURs, speed limit theorems, mismatch cost, all provide lower bounds on $\mathsf{EP}(p_0)$ arising from how a computer is used and how it performs.

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